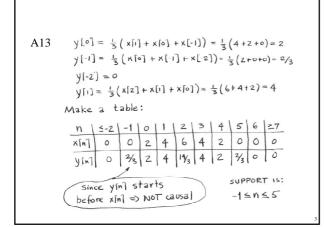


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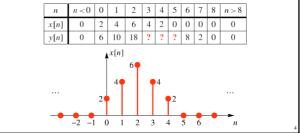
http://www.yildiz.edu.tr/~naydin

# Q13 Determine the output of a *centralized averager* y[n]=(1/3) (x[n+1] + x[n] + x[n-1])for the following input. Is this filter causal or noncausal? What is the support of the output for this input? ... y[n]=(1/3) (x[n+1] + x[n] + x[n-1])for the following input. Is this filter causal or noncausal? What is the support of the output for this input?



#### Q14

Compute the output y[n] for the length-4 filter whose coefficients are  $\{b_k\}=\{3,-1,2,1\}$ . Use the following signal as input. Verify that the answers tabulated here are correct, then fill in the missing values.



A14  

$$y[n] = 3x[n] - x[n-1] + 2x[n-2] + x[n-3]$$

$$b_{0} \qquad b_{1} \qquad b_{2} \qquad b_{3}$$

$$y[2] = 3x[2] - x[1] + 2x[0] + x[-1].$$

$$= 3(6) - 4 + 2(2] + 0 = 18$$

$$y[3] = 3x[3] - x[2] + 2x[1] + x[0]$$

$$= 3(4) - 6 + 2(4) + 2 = 16$$

$$y[4] = 3(2) - 4 + 2(6) + 4 = 18$$

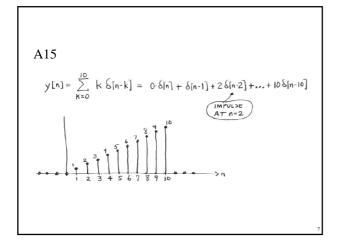
$$y[5] = 3(0) - 2 + 2(4) + 6 = 12$$

$$y[6] = 3(0) - 0 + 2(2) + 4 = 8$$

# Q15

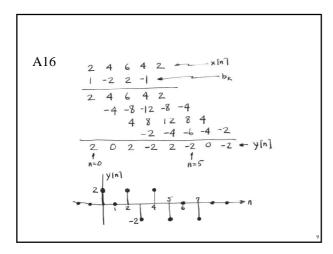
Determine and plot the impulse response of the FIR system

$$y[n] = \sum_{k=0}^{10} kx[n-k]$$



## Q16

Use the "synthetic multiplication" convolution algorithm to compute the output y[n] for the length 4 filter whose coefficients are  $\{b_k\} = \{1, -2, 2, -1\}$ . Use the input signal given below.

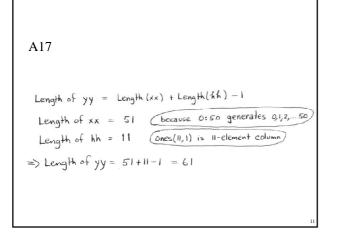


# Q17

In MATLAB, we can compute only the convolution of finite-length signals. Determine the length of the output sequence computed by the MATLAB convolution below.

xx = sin(0.07\*pi\*(0.50));hh = ones(11,1)/11; yy = conv(hh, xx);

-2 -1 0



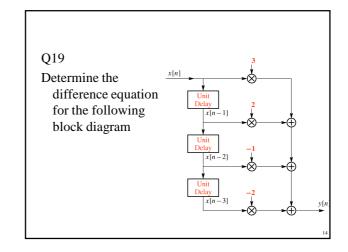
## Q18

Use MATLAB to compute the following product of polynomials:

$$P(x) = (1 + 2x + 3x^{2} + 5x^{4})(1 - 3x - x^{2} + x^{3} + 3x^{4})$$

A18  
In MATLAB, use conv() function  
conv([1,2,3,0,5], [1,-3,-1,1,3])  
(missing  
x<sup>3</sup> TERM)  
The answer computed by MATLAB is:  
[1,-1,-4,-10,7,-6,4,5,15]  
As a polynomial:  

$$1-x-4x^2-10x^3+7x^4-6x^5+4x^6+5x^7+15x^8$$

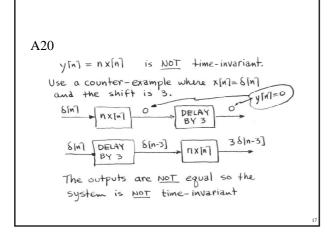


## A19

The outputs of the UNIT-DELAYS are already labelled, so each output is multiplied by a constant and then added to form y[n]. y[n] = -2x[n-3] + (-x[n-2] + (2x[n-1] + (3x[n])))= 3x[n] + 2x[n-1] - x[n-2] - 2x[n-3]The filter coefficients are:  $b_0 = 3$ ,  $b_1 = 2$ ,  $b_2 = -1$ , and  $b_3 = -2$ 

#### Q20

Test the system defined by the equation y[n] = nx[n] to determine whether it is a time-invariant system.



# Q21

Show that the time-flip system y[n] = x[-n] is a linear system.

A21  
Define 
$$FLIP\{x[n]\} = x[-n]$$
  
Scaling:  $FLIP\{ax[n]\} = ax[-n]$   
That is, "doubling  $x[n]$ " will double its flipped version  
Additive:  
 $FLIP\{x_1[n] + x_2[n]\} = x_1[-n] + x_2[-n]$   
 $= FLIP\{x_1[n]\} + FLIP\{x_2[n]\}$ 

By making the substitution k = n - l in the following equation,

$$y[n] = \sum_{l=n-M}^{n} x[l]h[n-l]$$

show that y[n] can also be expressed in the same form as

$$y[n] = \sum_{k=0}^{M} h[k]x[n-k]$$

A22 Start with  $y(n) = \sum_{l=n-M}^{n} h[n-l] x[l]$ With k=n-l, the limits on the sum are:  $l=n-M \implies k=n-l=n-(n-M)=M$   $l=n \implies k=n-l=n-n=0$  $\therefore y[n] = \sum_{k=0}^{M} h[k] x[n-k]$ 

#### Q23

Determine the impulse response h[n] of the 51point causal running averager and determine the impulse response  $\tilde{h}[n]$  for the 51-point centralized running averager.

