# **Digital Signal Processing**

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### Q1

Use the following trigonometric identity to derive an expression for  $\cos 8\theta$  in terms of  $\cos 9\theta$ ,  $\cos 7\theta$ , and  $\cos\theta$ .

 $\cos(x\pm y) = \cos x \cos y \mp \sin x \sin y$ 

A1

 $Cos 9\theta = cos(8\theta + \theta) = cos 8\theta cos \theta - sin 8\theta sin \theta$  $cos 7\theta = cos(8\theta - \theta) = cos 8\theta cos \theta + sin 8\theta sin \theta$ 

 $\cos 9\theta + \cos 7\theta = 2\cos \theta \cos 8\theta$  $\implies \cos 8\theta = \frac{\cos 9\theta + \cos 7\theta}{2\cos \theta}$ 

Q2 Plot the graph of the following function:  $s(t) = \begin{cases} 2t & 0 \le t \le \frac{1}{2} \\ \frac{1}{3}t(4-2t) & \frac{1}{2} \le t \le 2 \\ 0 & elsewhere \end{cases}$ 



# Q3

Considering the function given in question 2, derive an equation for  $x_1(t) = s(t-2)$  and plot the graph of the function.



### Q4

Considering the function given in question 2, derive an equation for  $x_2(t) = s(t+1)$  and plot the graph of the function.















### Q8

Demonstrate that expanding the real part of *exp*( $j(\alpha+\beta)$ ) = *exp*( $j\alpha$ )×*exp*( $j\beta$ ) will lead to the following identity.

 $\cos(\alpha + \beta) = \cos\alpha\cos\beta - \sin\alpha\sin\beta$ 

Also show that the following identity is obtained from the imaginary part.

 $\sin(\alpha + \beta) = \sin\alpha\cos\beta + \cos\alpha\sin\beta$ 



### Q9

Show that the following representation can be derived for the real sine signal:

$$A\sin(\omega_0 t + \phi) = \frac{1}{2} X e^{-j\pi/2} e^{j\omega_0 t} + \frac{1}{2} X^* e^{j\pi/2} e^{-j\omega_0 t}$$

where  $X = Ae^{i\phi}$ . In this case, the interpretation is that the sine signal is also composed of two complex exponentials with the same positive and negative frequencies, but the complex coefficients multiplying the terms are different from those of the cosine signal. Specifically, the sine signal requires additional phase shifts of  $\pm \pi/2$  applied to the complex amplitude *X* and *X*<sup>\*</sup>, respectively.



## Q10

Use  $A_k \cos(\omega_0 t + \phi_k) = A_k \cos \phi_k \cos(\omega_0 t) - A_k \sin \phi_k \sin(\omega_0 t)$ to show that the sum  $1.7 \cos(20\pi t - 70\pi/180) + 1.9 \cos(20\pi t + 200\pi/180)$ reduces to  $A \cos(20\pi t + \phi)$ , where

A = 1.532 and  $\phi = 2.475$  rads



#### Q11

Consider the two sinusoids,  $x_1(t) = 5 \cos(2\pi(100)t + \pi/3)$  $x_2(t) = 4 \cos(2\pi(100)t - \pi/4)$ 

Obtain the phasor representations of these two signals, add the phasors, plot the two phasors and their sum in the complex plane, and show that the sum of the two signals is  $x_3(t) = 5.536 \cos(2\pi(100)t + 0.2747)$ 

In degrees the phase should be 15:74. Examine the plots in Fig. 2-16 to see whether you can identify the cosine waves
x1.t/, x2.t/, and x3.t/ D x1.t/ C x2.t/.

A11  $I_{A}(t) = 5 \cos(2\pi(\iotao2t + \frac{1}{1}s_{A}) \Rightarrow Z_{a} - 5 e^{\frac{1}{2}N_{A}}$   $I_{A}(t) = 4 \cos(2\pi(\iotao2t - \frac{1}{2}t_{A}) \Rightarrow Z_{a} = 4e^{-\frac{1}{2}N_{A}}$   $I_{A}(t) = 4 \cos(2\pi(\iotao2t - \frac{1}{2}t_{A}) \Rightarrow Z_{a} = 4e^{-\frac{1}{2}N_{A}}$   $I_{A}(t) = 4 \cos(2\pi(\iotao2t - \frac{1}{2}t_{A}) \Rightarrow Z_{a} = 4e^{-\frac{1}{2}N_{A}}$   $I_{A}(t) = 4 \cos(2\pi(\iotao2t - \frac{1}{2}t_{A}) \Rightarrow Z_{a} = 4e^{-\frac{1}{2}N_{A}}$   $I_{A}(t) = 4 \cos(2\pi(\iotao2t - \frac{1}{2}t_{A}) \Rightarrow Z_{a} = 4e^{-\frac{1}{2}N_{A}}$   $I_{A}(t) = 5e^{-\frac{1}{2}N_{A}}$   $I_{A}(t) = 5e^{-\frac{1$ 

### Q12

Demonstrate that a complex exponential signal can also be a solution to the tuning-fork differential equation:  $d^2x/dt^2 = -(k/m)x(t)$ 

By substituting z(t) and  $z^*(t)$  into both sides of the differential equation, show that the equation is satised for all *t* by both of the signals  $z(t)=X e^{j\omega_0 t}$  and  $z^*(t)=X^*e^{j\omega_0 t}$ 

Determine the value of  $\omega_0$  for which the differential equation is satised.

A12  

$$\begin{array}{c} \underbrace{F_{IRST} \ DERIVATIVE:}{\frac{d}{dt} \ \overline{x}(t) = \ j\omega_{o} \ \overline{X} e^{j\omega_{o}t} \\ \frac{d}{dt} \ \overline{x}(t) = \ j\omega_{o} \ \overline{X} e^{j\omega_{o}t} \\ \underline{2ND \ DERIVATIVE:}{\frac{d^{2}}{dt^{*}} \ \overline{x}(t) = \ (j\omega_{o})^{2} \ \overline{X} e^{j\omega_{o}t} \\ \underbrace{\frac{d^{2}}{e^{j\omega_{o}t} \ \omega_{o}^{2}} \\ \frac{d^{2}}{dt^{*}} \ \overline{x}(t) = \ (j\omega_{o})^{2} \ \overline{X} e^{j\omega_{o}t} \\ \underbrace{\frac{d^{2}}{e^{j\omega_{o}t} \ \omega_{o}^{2}} \\ \underline{Tf} \ -\omega_{o}^{2} = -\frac{k}{m}, \ \text{then the differential equation} \\ \text{is satified} \ , \ \omega_{o} = \ \sqrt{\frac{k}{m}} \end{array}$$